**Calibration Procedure**

1. Read on screen instructions, the servo should begin around angle 0.
2. If it is beyond zero in the positive direction press switch 2 to rotate the servo backwards
3. If it is behind zero then press switch 1 to rotate the servo forwards
4. When the servo is at the desired angle press switch 4
5. Repeat these steps for all of the positions
6. The microcontroller will now preform its calculations
7. Running the check program should show the various positions